

Ang Li

Website: angli66.github.io
Email: angli66@stanford.edu

EDUCATION

Stanford University

M.S. Computer Science

Sep 2023 - Present

University of California, San Diego

B.S. Computer Science, GPA: 3.97 / 4.0

Aug 2019 - Dec 2022

PUBLICATION

- Xiaoshuai Zhang, Rui Chen, **Ang Li**, Fanbo Xiang, Yuzhe Qin, Jiayuan Gu, Zhan Ling, Minghua Liu, Peiyu Zeng, Songfang Han, Zhiao Huang, Tongzhou Mu, Jing Xu, Hao Su. *Close the Optical Sensing Domain Gap by Physics-Grounded Active Stereo Sensor Simulation*. Accepted to IEEE Transactions on Robotics (T-RO). [[arXiv](#)]

RESEARCH EXPERIENCE

Key Frame Editing for Robot Manipulation

Advisor: Prof. Hao Su

UC San Diego (Remote)

April 2023 - Present

- Designed a reward-based key frame editing framework for robot manipulation tasks.
- Built an ImGui-based UI for the system upon [SAPIEN](#).

Active Stereo Vision Depth Sensor Simulation

Advisor: Prof. Hao Su

UC San Diego

July 2022 - Nov 2022

- Developed a CUDA library to simulate the stereo matching module of real-world depth sensors. The library is integrated into [SAPIEN](#).
- Our proposed depth sensor simulation pipeline built on [SAPIEN](#) outperformed other state-of-the-art sim-to-real methods in both runtime performance and transfer performance. [[Project Page](#)]

Closed-Loop Control for Mechanical Ventilation

Advisor: Prof. Ryan Kastner

UC San Diego

Nov 2020 - June 2021

- Led the development of the closed-loop control circuit for a low-cost mechanical ventilator prototype.
- Designed and developed a PID controller implementing Pressure Control Ventilation on Arduino chips.

SELECTED PROJECTS

SAPIEN | [[GitHub](#)]

- SAPIEN is a realistic and physics-rich simulated environment. I developed [SAPIEN Realistic Depth](#), scene serialization and key frame editor for SAPIEN.

SimSense | [[GitHub](#)]

- Developed a Real-Time Depth Sensor Simulator with GPU Acceleration. The code can achieve 250+ FPS, which is 300x faster than off-the-shelf CPU implementations.

Neural Radiance Fields (NeRF) | [[GitHub](#)]

- Reimplemented NeRF in a concise manner using PyTorch.

Multi-view Stereo (MVS) | [[GitHub](#)]

- Developed a MVS reconstruction pipeline using OpenCV and Open3D.

TEACHING

CSE 152A: Introduction to Computer Vision

Instructional Assistant

UC San Diego

Sep 2022 - Dec 2022

- The course covered image formation, reconstruction, classification, recognition, deep learning.

VOLUNTEERING

Mentor for UC San Diego Regents Scholar Research Initiatives

Mentorship

UC San Diego

Oct 2022 – June 2023

- Support two prospective students interested in CV/RL research through biweekly meetings.

TECHNICAL SKILLS

Languages: Python, C/C++, Java, CUDA, MATLAB, SQL

Developer Tools: Git, Docker, Kubernetes, CMake

Libraries: PyTorch, OpenCV, Open3D, pybind11, ImGui